

# REAYER: Real-time Earthquake Prediction with Attention-based Sliding-Window Spectrograms

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## Abstract

Predicting earthquakes with precision remains an ongoing challenge in earthquake early warning systems (EWS), that struggle with accuracy and fail to provide timely warnings for impending earthquakes. Recent efforts employing deep learning techniques have shown promise in overcoming these limitations. However, current methods lack the ability to capture subtle frequency changes indicative of seismic activity in real-time, limiting their effectiveness in EWS. To address this gap, we propose REAYER, a novel approach for real-time prediction of P- and S-waves of earthquakes using attention-based sliding-window spectrograms. REAYER leverages Mel-Spectrogram signal representations to capture temporal frequency changes in seismic signals effectively. By employing an encoder-decoder architecture with attention mechanisms, REAYER accurately predicts the onset of P- and S-waves moments when an earthquake occurs. We benchmark the effectiveness of REAYER, showing its performance in terms of both accuracy and real-time prediction capabilities compared to existing methods. Additionally, we provide a web-based implementation of REAYER, allowing users to monitor seismic activity in real-time and analyze historical earthquake waveforms.

## 1 Introduction

Despite the pressing need to alert populations and safeguard essential infrastructure, up til now it is not possible to predict specific earthquakes with certainty, e.g., the Turkey–Syria earthquakes in 2023 [Kwiatkiewicz *et al.*, 2023]. Existing earthquake early warning systems (EWS) like the ShakeAlert system used in US West Coast [Kohler *et al.*, 2020] use on-site  $\tau_c - P_d$  algorithm to estimate the arrival of a P-phase, which is the primary seismic wave produced by an earthquake. This algorithm is based on  $\tau_c$  parameter that captures the wave’s dominant period and  $P_d$  for its initial amplitude, in combination with classic short-term average and long-term average (STA/LTA) detection approaches [Gao *et al.*, 2021]. Those approaches are limited in their accuracy as

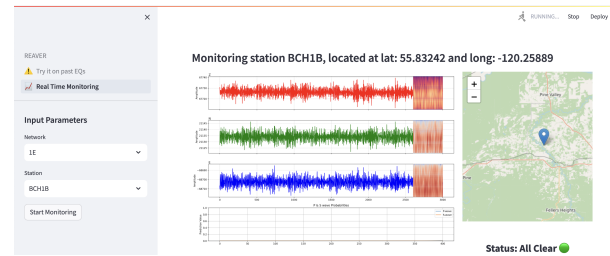


Figure 1: REAYER’s interface, showing real-time monitoring of seismic activity at station BCH1B in Canada. It illustrates Mel-Spectrogram visualizations for three channels (Z, N, E) and the probabilities of P and S waves, with a map indicating the station’s location.

well as the time period between warning and occurrence of the earthquake; furthermore, they cannot generalize to earthquake signals from other regions [Lara *et al.*, 2023].

Recently, deep learning methods were applied to overcome those limitations in EWS. Several methods use fully-connected network, CNNs and RNNs applied on the raw earthquake waveforms to classify between earthquakes and impulsive noises [Ku *et al.*, 2020; Fauvel *et al.*, 2020; Huang *et al.*, 2020; Meier *et al.*, 2019; Mallouhy *et al.*, 2019] or to estimate the magnitude of earthquakes and its source characterization [Munchmeyer *et al.*, 2021; Ochoa *et al.*, 2018]. Furthermore, CNN-based architectures are applied to phase-picking for predicting arrival times of P waves as well as S waves, i.e., more destructive secondary or shear waves of earthquakes, e.g., PhaseNet [Zhu and Beroza, 2019]. This approach is extended by the EQTransformer by employing a combination of CNNs, RNNs and Transformer attention applied on longer 60-seconds waveforms [Mousavi *et al.*, 2020]. While such methods show high detection accuracy of P and S waves, they are trained with raw long waveforms containing centered P or S waves from the earthquake signal. Other methods combine CNN-RNN architectures with Mel-Spectrograms for binary earthquake classification [Shakeel *et al.*, 2021; Mukherjee *et al.*, 2021]. These methods do not capture the instant tiniest changes in frequency when an earthquake occurs and limits their performance in EWS to enable real-time detection of an earthquake. But, predicting an earthquake even just a second before it happens can have significant positive impacts on reducing damage and en-

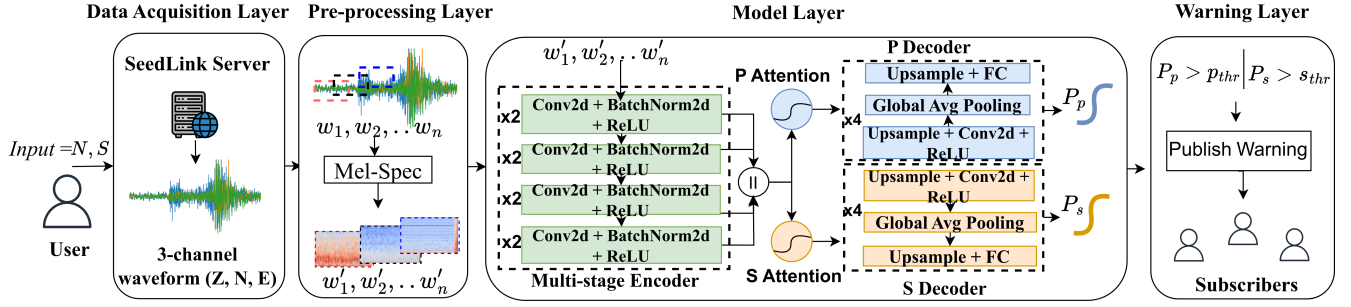


Figure 2: REAVER’s Architecture with its four layers: Data Acquisition, Pre-Processing, Model Prediction, and Warning Generation.

hancing public safety [McBride *et al.*, 2022], e.g., automated systems activation like shutting off gas lines, brief warnings for allowing people to take cover under a desk or move away from windows and switch of life-support systems in hospitals to emergency power to ensure continuity.

In this paper, we propose REAVER - an approach for predicting P- and S-waves of earthquakes in real-time based on attention-based sliding-window spectrograms. Instead of relying on raw 3-channel waveforms, we adopt the widely used Mel-Spectrogram signal representation in sound to represent the frequency amplitudes in each channel in the signal across time [Gong *et al.*, 2022; Meng *et al.*, 2019]. Combined with a sliding window approach, we are able to instantly capture the temporal frequency changes in the signal using an encoder equipped with attention based separate decoders for the continuous probabilities of P and S waves. REAVER not only significantly enhances detection speed, needing only 0.08 seconds of the waveform to predict P-waves with up to 70% faster than existing approaches, but also achieves a higher classification accuracy of 98.81%. The proposed approach was implemented into a web-based EEWs that allows users to monitor seismic stations for real-time earthquake warnings or to analyze past earthquake waveforms (cf. Fig. 1). The source code of REAVER is available at the following GitHub repository<sup>1</sup> along with a demonstration video showing how it works<sup>2</sup>.

## 2 System Overview

REAVER is composed of 4 layers: 1) Data acquisition layer that gets real-time and historical waveforms, 2) Pre-processing layer which divides the signal into overlapping windows and computes the Mel-Spectrogram for each window, 3) Model layer which predicts the continuous probabilities of P and S waves, and 4) Warning layer which publishes warnings to subscribers when the detection of P or S waves exceeds a threshold to take an instant response (cf. Fig. 2).

### 2.1 Data Acquisition Layer

The data acquisition layer is responsible for collecting the historical waveform data for model training and real-time data

from seismic stations for inference. For real-time data acquisition, the user chooses a network and a station from an inventory provided by Obspy<sup>3</sup> - a python package for seismology. The chosen variables are encapsulated within a request to acquire real-time data from IRIS real-time server<sup>4</sup> for later processing. For model training, the layer collects historical waveforms data from STEAD [Mousavi *et al.*, 2019], which contains 1.2 million earthquake and noise waveforms with a sampling rate of 100 Hz. Each waveform is represented as 3-channel time-series  $X_c(t)$  where  $c$  corresponds to the vertical (Z), north-south (N), and east-west (E) components of seismographs.

### 2.2 Pre-Processing Layer

The pre-processing layer receives the raw waveform and slices it into overlapping windows across each channel. Unlike [Mousavi *et al.*, 2020; Zhu and Beroza, 2019] which use the full raw waveform, the slicing approach allows a more detailed and continuous analysis of the signal over time, which is crucial for real-time EEWs. Formally, we segment each channel into overlapping windows as follows:

$$S = W - \left( \frac{O}{100} \times W \right), \quad N = 1 + \left\lfloor \frac{L - W}{S} \right\rfloor \quad (1)$$

where  $S$  is the step size,  $W$  is the window length,  $\frac{O}{100}$  is the overlap percentage,  $L$  is the length of each channel in the signal, and  $N$  is the total number of windows per channel. The output is a list of windows  $w_i^c = X_c[s_i : e_i]$  for each channel  $c$  and window  $i$ , where  $s_i$  and  $e_i$  are the start and end indices of the  $i^{th}$  window, respectively. Instead of using the raw waveform of signal amplitudes, we convert the signal in each window into its Mel-Spectrogram representation by computing the Short-Time Fourier Transform (STFT) as follows:

$$\text{STFT}\{x(t)\}(m, \omega) = \sum_{n=-\infty}^{\infty} x(n) \cdot w(n - m) \cdot e^{-j\omega n} \quad (2)$$

where  $w(n)$  is the window function,  $m$  is the time index, and  $\omega$  is the frequency index. Then, a set of  $k$  triangular filters

<sup>1</sup><https://github.com/InformationServiceSystems/pairs-project/tree/main/Modules/CrisisImaginators/REAVER>

<sup>2</sup><https://www.youtube.com/watch?v=PIRmRzfN-k>

<sup>3</sup><https://github.com/obspy/obspy/wiki/>

<sup>4</sup><https://www.iris.edu/hq/sage>

$\{H_k(m)\}$  is applied to the STFT, where each filter corresponds to a Mel frequency. The log Mel-Spectrogram for each window is then obtained as:

$$w_i^c = \log \left( \sum_m |\text{STFT}\{w_i^c(t)\}(m, \omega)| \cdot H_k(m) \right) \quad (3)$$

where  $c$  is the channel index.

### 2.3 Model Layer

The model layer takes input the Mel-Spectrogram windows for each channel  $w'$  and passes it to an encoder-decoder model. The model is composed of a multi-stage encoder, an attention layer for each stage, and two separate decoders for P and S waves. The encoder consists of 4 stages, where each stage  $S_i$  is defined as a sequence of two blocks. Each block applies a Conv2D layer followed by BatchNorm2d and ReLU activation function. Given the set of Mel-Spectrogram windows  $W'$ , the operation of a single block can be represented as:

$$\text{Block}(W') = \text{ReLU}(\text{BatchNorm2d}(\text{Conv2d}(W')))$$

Therefore, each stage in the encoder can be expressed as the composition of two such blocks:

$$S_i = \text{Block}(\text{Block}(W'_i))$$

where  $W'_i$  is the output from the previous stage or the input to the encoder for  $i = 1$ . Subsequently, P Decoder and S Decoder each apply spatial self-attention to the outputs from each encoder stage, which can be written as:

$$\text{Attn}(S_i) = \text{Conv2d}(S_i \odot \sigma(\text{Conv2d}(S_i)))$$

where  $\sigma$  denotes the sigmoid function and  $\odot$  represents element-wise multiplication. The attention mask generated by the sigmoid function modulates the feature map for each branch to focus on relevant features for P and S waves separately. Each decoder consists of sequences of such  $\text{Attn}()$  layers followed by upsampling and convolution operations. Formally, for each stage  $S_i$  of the encoder, the corresponding decoder block output can be represented as:

$$D_i = \text{Upsample}(\text{Conv}(\text{Attn}(S_i)))$$

where  $D_i$  is the output of the  $i$ -th decoder block. Finally, the continuous probabilities for P and S wave, denoted as  $P_p$  for the P Decoder and  $P_s$  for the S Decoder, can be expressed as:

$$P_p = \text{FC}(\text{Upsample}(\text{GlobalAvgPool}(D_P)))$$

$$P_s = \text{FC}(\text{Upsample}(\text{GlobalAvgPool}(D_S)))$$

where  $D_P$  and  $D_S$  are the aggregated outputs of the P Decoder and S Decoder blocks, respectively. We utilize BinaryCrossEntropy loss for supervising both  $P_p$  and  $P_s$ .

### 2.4 Warning Layer

The warning layer evaluates the probabilities  $P_p$  and  $P_s$  from the model layer and issues warnings to subscribers, including individuals or government entities, when  $P_p > P_{\text{thr}}$  or  $P_s > S_{\text{thr}}$ .  $P_{\text{thr}}$  and  $S_{\text{thr}}$  are hyperparameters which are set to 0.7 upon extensive experiments to optimize the precision-recall trade-off.

Method	$\Delta t_{\text{mean}}$ (s)	$\sigma_{\Delta t}$ (s)	Median (s)	Q1 (s)	Q3 (s)
PhaseNet	1.67	2.01	0.83	0.59	1.93
EQTransformer	3.73	4.48	1.62	1.20	4.00
STA/LTA	0.27	0.31	0.15	0.04	0.40
REAYER	<b>0.08</b>	<b>0.16</b>	<b>0.04</b>	<b>0.03</b>	<b>0.12</b>

Table 1: Performance comparison of P-wave detection time statistics, showing the mean time difference  $\Delta t_{\text{mean}}$ , standard deviation  $\sigma_{\Delta t}$ , median  $\Delta t_{\text{median}}$ , 25th percentile (Q1)  $\Delta t_{25\%}$ , and 75th percentile (Q3)  $\Delta t_{75\%}$ .

Method	Precision	Recall	F1 Score	Accuracy (%)
PhaseNet	0.98	0.96	0.97	95.46
EQTransformer	0.99	0.91	0.95	92.50
STA/LTA	0.96	0.85	0.89	85.56
REAYER	<b>0.99</b>	<b>0.98</b>	<b>0.99</b>	<b>98.81</b>

Table 2: Classification performance on the testing dataset.

## 3 Evaluation

To evaluate our method we use a dataset consisting of 51,510 earthquakes and 11,773 noise waveforms from STEAD. We simulate real-time detection by applying a 4-second sliding window with 99% overlap before the P- and S-wave arrival times. We compare our method against classical STA/LTA method [Choubik *et al.*, 2020], and deep learning methods PhaseNet [Zhu and Beroza, 2019] and EQTransformer [Mousavi *et al.*, 2020] which were originally trained using 30- and 60-second windows respectively. We apply the same sliding window configuration across all methods for a fair comparison. In our evaluation, we prioritize two critical dimensions of earthquake detection performance: the speed of P-wave detection and the accuracy of distinguishing between earthquake and noise waveforms. Speed of detection is assessed through  $\Delta t$ , representing the time difference between the algorithm’s detection of the P-wave and its actual occurrence. Additionally, we evaluate classification accuracy, measuring each method’s ability to correctly identify earthquake waveforms against impulsive noise. Table 1 shows the distribution statistics of  $\Delta t$  over the testing dataset for all the methods. We observe that REAYER significantly enhances detection timeliness, improving by 70% over STA/LTA and around 95% over PhaseNet and EQTransformer in mean detection time difference ( $\Delta t_{\text{mean}}$ ). In Table 2, we show the classification performance of differentiating between earthquake and noise waveforms, recording a correct detection when either a P or S wave was detected in the waveform. We observe that REAYER outperforms other methods in accurately detecting earthquakes with overall accuracy 98.81%.

## 4 Conclusion

In this paper, we proposed REAYER, a novel method for real-time earthquake prediction utilizing attention-based sliding-window spectrograms. Our evaluation demonstrates that our method not only achieves high accuracy in differentiating earthquakes from noise, but also offers faster detection times compared to existing methods. REAYER’s web-based implementation allows for real-time earthquake monitoring and historical waveform analysis, making it a valuable tool for both individuals and professionals in seismology.

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