# Recurrent Concept Drifts on Data Streams

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#### Abstract

In an era where machine learning permeates every facet of human existence, and data evolves incessantly, the application of machine learning models transcends mere data processing. It involves navigating constant changes exemplifed by the phenomenon of concept drift, which often affects model performance. These drifts can be recurrent due to the cyclic nature of the underlying data generation processes, which could be infuenced by recurrent phenomena such as weather and time of the day. Stream Learning on data streams with recurrent concept drifts attempts to learn from such streams of data. The survey underscores the signifcance of the feld and its practical applications, delving into nuanced defnitions of machine learning for data streams afficted by recurrent concept drifts. It explores diverse methodological approaches, elucidating their key design components. Additionally, it examines various evaluation techniques, benchmark datasets, and available software tailored for simulating and analysing data streams with recurrent concept drifts. Concluding, the survey offers insights into potential avenues for future research in the feld.

## 1 Introduction

With the emergence of Industry, 4.0, more and more processes are monitored digitally, thus continuously generating tremendous quantities of data [\[Dreyfus](#page-7-0) *et al.*, 2022]. Data accessibility enables the implementation of impactful online data-driven machine learning models [\[Dreyfus](#page-7-0) *et al.*, [2022\]](#page-7-0). However, these data-driven models are impacted by concept drifts: input distribution shifts in the underlying data [\[Dreyfus](#page-7-0) *et al.*, 2022]. Concept drifts can differ due to impact, transition type, reach of change, recurrence, and blips/outliers/noise [\[Gunasekara](#page-7-1) *et al.*, 2023].

The literature describes real and virtual concept drifts considering *impact*. The former affects the decision boundary of the model. The latter does not infuence the decision boundary. Hence, the model is unaffected [\[Gunasekara](#page-7-1) *et al.*,

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Figure 1: Recurrent concept drifts by concept transition.

[2023\]](#page-7-1). Concerning *transition type*, the drifts are categorized into sudden (abrupt), gradual, and incremental drifts, considering the evolution of the relationship between features and the target and the speed of change. In sudden or abrupt drifts, the current data distribution changes to a new one within a short period [\[Gunasekara](#page-7-1) *et al.*, 2023]. For gradual drifts, this transition happens gradually [Suárez-Cetrulo et al., 2023]. Here, one could observe instances from both distributions for a certain period. The transition time is very long for incremental drifts [\[Gunasekara](#page-7-1) *et al.*, 2023]. With *recurrent concept drifts*, a particular data distribution reoccurs in the stream after a certain period. Recurrent concept drifts could also have different transition types going from one distribution to another. Literature also categorizes concept drifts considering their *reach of change*: drifts that affect all of the features are regarded as global drifts, and drifts that affect some of the features are called local drifts [Suárez-Cetrulo *et al.*, 2023]. *Random blips/outliers/noise* are situations where, for a very short period, few instances do not belong to the current distribution popup in the stream [Suárez-Cetrulo *et al.*, 2023].

This survey mainly focuses on recurrent concept drifts. Due to the cyclic nature of many physical phenomena, Stream Learning (SL) methods that can handle recurrent concept drifts were used in many real-world applications. A SL method that supports recurrent concept drifts was used to detect air quality using readings of neighboring sensors [\[Hal](#page-7-2)stead *et al.*[, 2022b\]](#page-7-2). Here, inference in air quality data was complex due to spatial non-linearities and abrupt temporal changes. Spatiotemporal relationships, environmental and contextual features such as meteorological conditions (wind), urban activity (traffc and heater use), and points of interest (locations of factories) were not available for the model. Thus, the model was required to adapt to these recurrent contexts dynamically. Furthermore, [SL](#page-0-0) with recurrent concept drifts support were used in two energy optimization problems [Wu *et al.*[, 2023\]](#page-8-1). The frst, tries to optimize between energy storage and energy usage during tariff periods. The second one attempts to predict HVAC (heating, ventilation, and air conditioning) electricity, considering factors such as temperature and humidity. Factors such as seasonality and human activity induce recurrent concept drifts in both cases. In another real-world problem, per-concept models were used to predict the outlet temperature in a Vertical Roller Mill system with recurring concepts due to regulating strategies [\[Sun](#page-8-2) *et al.*[, 2021\]](#page-8-2). Depending on the regulating strategy, previous concepts could reemerge. In another instance where species activity registered on a sensor that changed depending on the time of the day, custom models related to each species produced better results in determining the species than a generic model [\[Moreira dos Reis](#page-8-3) *et al.*, 2018]. Furthermore, recent research on data-driven model maintenance in industry 4.0 highlights the importance of [SL](#page-0-0) on data streams with recurrent concept [\[Dreyfus](#page-7-0) *et al.*, 2022].

Considering the above and many real-world applications, this survey focuses on [SL](#page-0-0) for data streams with recurrent concept drifts. The survey by [Suárez-Cetrulo et al., 2023] mainly focuses on [SL](#page-0-0) in general and explains different methods to handle recurrent concept drifts. However, it did not discuss evaluation methods, benchmark datasets, and software implementations for [SL](#page-0-0) on data streams with recurrent concept drifts. A recent survey [\[Gunasekara](#page-7-1) *et al.*, 2023] looks at [Online Continual Learning \(OCL\)](#page-0-0) from a [Stream Learning](#page-0-0) perspective. Though it refers to [Suárez-Cetrulo *et al.*, 2023] for the latest [SL](#page-0-0) work for recurrent concept drifts, the main emphasis there is how [SL](#page-0-0) could improve [Online Continual](#page-0-0) [Learning.](#page-0-0) Hence, it misses a thorough investigation of [SL](#page-0-0) on data streams with recurrent concept drifts. This survey attempts to fll the above-mentioned survey gaps by explaining design components, evaluation methods, benchmark datasets, and software implementations for [SL](#page-0-0) on data streams with recurrent concept drifts. The survey also dwells into similar settings such as concept evolution with recurrent classes for [SL](#page-0-0) and [Online Continual Learning](#page-0-0) to fnd intersections and differences with those research felds.

This paper is structured as follows. First, we provide definitions of recurrent concept drifts. Considering their design components we explain popular [SL](#page-0-0) methods for recurrent concept drifts in the following section. In the subsequent sections, we explore different evaluation methods, open-source software, benchmark datasets and future directions. Concluding remarks are presented in the fnal section.

## <span id="page-1-1"></span>2 Problem Statement

Consider an online learning algorithm A learning from an online (potentially infnite) non[-Independent and Identically](#page-0-0) [Distributed \(](#page-0-0)IID) data stream. Here, the data stream can be defined as a stream of unknown distributions  $D =$  $D_1, D_2, \ldots, D_N$  over  $X \times Y$ , where X and Y are input and output random variables. The transition of  $D_j \to D_{j+1}$ 

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Figure 2: Recurrent concept drifts by time of recurrence.

could happen such that  $D_j \neq D_{j+1}$ , to result in a *concept drift* [Gama *et al.*[, 2014\]](#page-7-3). Specifcally, it is a drift in the conditional probability distributions, where  $P_j(y|X) \neq$  $P_{j+1}(y|X)$  [Gama *et al.*[, 2014;](#page-7-3) Gao *et al.*[, 2020\]](#page-7-4). Furthermore, if  $D_{j-k} = D_{j+1}$ , this new distribution can be considered a recurrence of a  $k$ -th previous distribution. Such a drift is identified as a *recurrent concept drift* in literature [Suárez-[Cetrulo](#page-8-0) *et al.*, 2023].

Recurrent concept drifts could also have different transition types going from one distribution to another. Figure [1a](#page-0-1) illustrates *abrupt recurrent concept drifts*. Here, the distribution shifts from one concept to the other are abrupt. On the other hand, fgure [1b](#page-0-1) explains *incremental recurrent concept drifts*, where instances slowly change over to the new concept from the previous concept, and this incremental transition of concepts is present throughout the recurrent drifts. With *gradual recurrent concept drifts*, concepts change gradually. During the drift period, instances from both concepts appear in the stream for some time. This is illustrated in fgure [1c](#page-0-1) with instances from the blue concept appearing in the stream with the pink concept until it completely switches over to the pink concept. Then, again, instances slowly transition into the blue concept while instances from the pink concept gradually disappear from the stream. *Partial recurrent concept drifts* are when a given recurrent concept is only seen partially at the subsequent recurrence. For example, in fgure [1d](#page-0-1), the pink concept is partially present in the subsequent recurrence, while the blue concept is fully present in the next recurrence. Figure [1e](#page-0-1) explains an *evolving recurrent concept drift* where a given recurrent concept slowly evolves into a new concept over a period of time. Here, one can see the pink recurrent concept slowly evolving into the orange concept throughout the recurrences.

On the other hand, the recurrence of a given concept could have many forms, depending on the time of recurrence. As shown in fgure [2a](#page-1-0), recurrences follow a periodic pattern in *periodic recurrent drifts*. Seasonal weather changes are a good example of periodic recurrent drifts, where each season occurs around the same time of the year. In *semi-periodic recurrent drifts*, only certain concepts reoccur periodically. For example, in fgure [2b](#page-1-0), only the blue concept reoccurs regularly, while other concepts follow a random recurrence pattern. The recurrence pattern for each concept is hard to determine in a data stream with *random recurrent drifts*. This is illustrated with random recurrences for each concept in fgure [2c](#page-1-0).

Researchers working in the feld should be aware of the different intricacies in recurrent concept drifts, considering drift transition type and concept recurrence pattern which is highlighted in fgures [1](#page-0-1) and [2.](#page-1-0)

# <span id="page-2-3"></span>3 Handling Recurrent Concept Drifts

The literature identifes many methods to detect drifts in the input distribution: *methods based on differences between two distributions*, *methods based on sequential analysis* and *methods based on statistical process control* [\[Gu](#page-7-1)[nasekara](#page-7-1) *et al.*, 2023]. Works by [\[Khamassi](#page-8-4) *et al.*, 2018] and [Gama *et al.*[, 2014\]](#page-7-3) contain thorough reviews of drift detectors for [Stream Learning.](#page-0-0) Once a drift is detected, they discuss many methods to identify recurrent concepts. *Conceptual equivalence* assumes when two classifers behave similarly in prediction for a time window, both classifers describe the same concept [Yang *et al.*[, 2006\]](#page-8-5). The idea of *concept similarity* was initially proposed in REDLLA [\[Li](#page-8-6) *et al.*[, 2012\]](#page-8-6) to detect recurring drifts in the absence of labeled data. Though the authors did not name this as such, the approach aimed to recognize similar concepts using Euclidean distances between concept clusters representing different concepts. Different distance measures for concept similarity are discussed in other research [Angel *et al.*[, 2016;](#page-7-5) Gomes *et al.*[, 2013\]](#page-7-6). RCD [Goncalves Jr and De Barros, [2013\]](#page-7-7) holds a pool of buffers and compares the current buffer against all to fnd similar concepts using a multivariate nonparametric statistical test.

Managing a *concept history* [Yang *et al.*[, 2006;](#page-8-5) [Alippi](#page-7-8) *et al.*[, 2013\]](#page-7-8), which contains a classifer for each concept, is popular among the research community. This idea of a *concept history* is described using different terminology like *pool of classifers* [\[Hosseini](#page-8-7) *et al.*, 2013], *concept list* [Li *et al.*[, 2012\]](#page-8-6) and *concept repository* [Wu *et al.*[, 2021;](#page-8-8) Wu *et al.*[, 2022\]](#page-8-9) in [SL](#page-0-0) for data streams with recurrent concept drifts.

## <span id="page-2-0"></span>3.1 Explicit Handling of Recurrences

Some [SL](#page-0-0) methods that deal with recurrent concept drifts build a classifer for each data batch and use a repository/ensemble management technique to maintain the repository/ensemble. These methods do not employ a drift detector to detect drifts. LEARN++.NSE trains a new classifer for each batch of data and combines the classifers using weighted voting [\[Elwell and Polikar, 2011\]](#page-7-9). For recurring concepts, it assumes that the weights of learners relating to the recurrent concept will increase, and therefore, the fnal prediction will consider relevant knowledge. PMRCD also builds a classifer for each data batch. The method maintains a pool of ensembles for each concept [\[Hosseini](#page-8-10) *et al.*, [2012\]](#page-8-10). A maximum number of concepts and classifers were assumed to handle the memory limitations. The authors proposed a mechanism to manage the classifer pool by merging and splitting concepts. A similar approach of maintaining a classifer pool and selecting the best ensemble was discussed in Dynse [\[Almeida](#page-7-10) *et al.*, 2018]. ASE also considered dynamically handling the ensemble size for recurrent concept drifts [Duda *et al.*[, 2017\]](#page-7-11). Considering the current data chunk, it evaluates whether adding an item to the ensemble increases the accuracy for the entire data stream. The method uses Kullback-Leibler discrepancy to measure the suitability of the elements. GraphPool [\[Ahmadi and Kramer, 2018\]](#page-7-12) maintains a pool of concepts by applying a merging mechanism whenever necessary: after receiving a new batch of data, it extracts a concept representation considering the correlation among features. Then, it compares the current representation to the representations in the pool using a statistical multivariate likelihood test. GraphPool merges all the corresponding concepts if they are similar. Like PMRCD, it also uses Naïve Bayes classifers. Furthermore, GraphPool maintains the transition among concepts via a frst-order Markov chain. This information is used in prediction. It can use either a single classifer or a weighted majority vote among classifers for prediction.

## <span id="page-2-1"></span>3.2 Meta Learning

Independently of the number of base learners, some [SL](#page-0-0) methods for recurrent concept drifts act as a wrapper algorithm to determine the best model or models for the current concept after detecting a drift. Thus, they act as metalearners [Suárez-Cetrulo *et al.*, 2023]. RCD creates a new classifer for each concept and stores a sample of data used to build it [Gonçalves Jr and De Barros, 2013]. When it detects a new concept, the algorithm compares the incoming data to previous ones using a non-parametric multivariate statistical test to verify if both contexts come from the same distribution. If so, the corresponding classifer is reused. Concept Profling Framework (CPF) [\[Anderson](#page-7-13) *et al.*, 2016] handles recurring concepts using a classifer pool. It evaluates which model to reuse when a concept drift is detected using conceptual equivalence with classifcation accuracy. New models are added into the pool in case of a drift and pruned considering their reuse frequency. CPF is shown to be very effective on synthetic data with clear recurrent drifts but fails to outperform RCD on real-world benchmarks [\[Anderson](#page-7-14) *et al.*, 2019]. One of the limitations of CPF is that it relies on a fxed buffer size to determine what model to reuse. This makes it slower to react to drift than the other approaches [\[Anderson](#page-7-14) *et al.*, 2019]. An enhanced version of CPF was proposed in ECPF [\[Ander](#page-7-14)son *et al.*[, 2019\]](#page-7-14). It trains both a new and used classifer on new data and retains the more accurate classifer when concept drift occurs. ECPF creates a copy of the old classifer so that training on new data does not impact the old classifer. PEARL [Wu *et al.*[, 2022\]](#page-8-9) utilizes an exact technique and a probabilistic graphical model with Lossy Counting to replace drifted trees in an ensemble with relevant trees from a repository. The exact technique uses pattern matching to fnd the set of drifted trees that co-occurred in the past for predictions. At the same time, the probabilistic graphical model captures tree replacements among recurrent concept drifts and replaces the exact technique when stable.

## <span id="page-2-2"></span>3.3 Concept Clusters

Unsupervised concept representations and distance metrics for concept similarity were also used by the [SL](#page-0-0) community working on data streams with recurrent concept drifts to identify recurrences [Li *et al.*[, 2012;](#page-8-6) Wu *et al.*[, 2012;](#page-8-11) Gomes *et al.*[, 2012\]](#page-7-15). In REDLLA [Li *et al.*[, 2012\]](#page-8-6), when growing a tree, the k-Means clustering algorithm produces concept clusters and labels unlabeled data at the leaves. The deviation between current and historic concept clusters was used to identify concept drifts and recurring concepts. A similar approach was proposed in SUN [Wu *et al.*[, 2012\]](#page-8-11). There instead of  $k$ -Means, authors used  $k$ -Modes as the clustering algorithm. A framework using the Context Spaces Model with Context Information was proposed in ContexTrac to represent different concepts [\[Gomes](#page-7-15) *et al.*, 2012]. However, they did not elaborate on a method to extract Context Information from a concept. A clustering-based semi-supervised framework, ESCR [\[Zheng](#page-8-12) *et al.*, 2021], uses Jensen Shannon divergence on classifcation confdence score [\[Haque](#page-8-13) *et al.*, [2016\]](#page-8-13) to detect recurrent concept drifts. It detects recurring concept drift by looking for any signifcant change in classifer confdence scores. Then, it determines the possibility of recurring concept drift via Jensen-Shannon divergence by calculating the distance between two confdence score distributions. ESCR performed better than REDLLA and RCD on some synthetic datasets. However, its performance was poor compared to other baselines when the dataset contains irrelevant attributes. CDMSE [Li *et al.*[, 2021\]](#page-8-14) works with missing labeled data. There, the predicted class labels by an ensemble model were partitioned into clusters for each data chunk to infer their class labels. Then a concept drift detection method based on the divergence of distributions between adjoining data chunks was used to distinguish recurring concept drifts. The method performed slightly better than SUN and REDLLA on different percentages of unlabeled data. CCP [\[Katakis](#page-8-15) *et al.*, 2010] is a very early method that used data stream clustering for [SL](#page-0-0) on data streams with recurrent concept drifts. It proposes a general framework for classifying data streams by exploiting stream clustering to build and update an ensemble of incremental classifers dynamically. Data stream clustering framework UClust [\[Namitha and San](#page-8-16)[thosh Kumar, 2020\]](#page-8-16) was proposed to handle unlabeled data streams with recurrent concepts. Clusters detected through CluStream [\[Aggarwal](#page-7-16) *et al.*, 2003] were used to detect drifts and identify concept recurrences. In the CDCMS framework, clustering in the model space was used to build a diverse ensemble and identify recurring concepts [\[Chiu and Minku,](#page-7-17) [2020\]](#page-7-17). The authors argue that diversity accelerates adaptation to different types of drifts when the new concept is similar to the past concepts.

## <span id="page-3-0"></span>3.4 Drift Prediction

Some methods attempt to predict the next drift or the concept, considering the recurrent nature of the concept's appearance in the stream. These methods try to either proactively infuence the drift detection mechanism or re-actively correct the detection signal by the drift detector. MM-PRec [Angel *et al.*[, 2016\]](#page-7-5) trains a meta-learner that uses a Hidden Markov Model to predict when a drift will happen and the most suitable concept for each situation if it is recurrent. To measure concept similarity, the authors used a function based on fuzzy logic. The extra computing required to train the meta-model was identifed as the method's main drawback. Predictive Change Confdence Function (PCCF) for modeling recurrent changes and predicting change points was derived using the average time between changes and its standard deviation [\[Maslov](#page-8-17) *et al.*, 2016].The PCCF mod-

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Table 1: Design components of the proposed methods for recurrent concept drifts in each section (Sec). DD: Drift Detection, DP: Drift Prediction, LM: Labels Missing, LN/A: Labels Not Available, MetaL: Meta Learning, MetaF: Meta Features, Clust: Clustering CEqSim: Conceptual Equivalence/Concept Similarity, Ens: Ensemble, CPool: Concept Pool. LEARN++\*: LEARN++.NSE

els recurrent streams as convolutions of Gaussian distributions of the time intervals between changes. The method can be used to post-process a detection by a drift detector or dynamically adjust the sensitivity of a drift detector. Later, BLPA [\[Maslov](#page-8-18) *et al.*, 2017] used PCCF to improve Bayesian Online Change Point Detector (BOCPD) [\[Adams](#page-7-18) [and MacKay, 2007\]](#page-7-18) for recurrent concept drifts. BOCPD was also used to develop Change Point Recurrence Distribution (CPRD) as an empirical estimate of the recurrent behavior of observed change points [Reich *et al.*[, 2019a;](#page-8-19) Reich *et al.*[, 2019b\]](#page-8-20). ProSeed [Chen *et al.*[, 2016\]](#page-7-19) uses a probabilistic network that uses stream volatility patterns to predict future changes. Like PCCF, this method also works independently of the drift detection technique. ProSeed was incorporated into the drift detector SEED [\[Huang](#page-8-21) *et al.*, 2014] to yield a proactive drift detector. Experimental results showed that ProSeed performed better than reactive drift detectors for data streams with reoccurring volatility trends. The same approach was used in ProChange [Koh *et al.*[, 2018\]](#page-8-22) to improve a drift detector using Hellinger distance to detect virtual drifts and Hoeffding inequality to detect real drifts for unlabeled transactional data. Metadata Drift Predictor (MDP) proposes a dynamically adapting drift detector using drift-related metadata clustering [\[Anderson](#page-7-20) *et al.*, 2018]. MDP allows the drift detector to be more sensitive when metadata is similar to past drifts and more conservative when metadata is dissimilar. In their empirical evaluations, MDP performed more accurately compared to ProSeed. Nacre proposes a framework that contains a recurrent drift classifer, a sequence predictor, and a drift coordinator for smooth adaptation of recurrent concept drifts [Wu *et al.*[, 2021\]](#page-8-8). The recurrent drift classifer maintains a concept repository for previously learned concepts. The drift sequence predictor predicts the next drift point based on the previous drift intervals. The drift coordinator manipulates the recurrent drift classifer and the drift sequence predictor to adapt to drifts proactively. Nacre uses PEARL [Wu *et al.*[, 2022\]](#page-8-9) as the recurrent drift classifier.

## <span id="page-4-0"></span>3.5 Meta Features

Apart from performance statistics such as accuracy, error rate, kappa, area under the curve, or classifer confdence score, some methods use different meta-features to improve [SL](#page-0-0) on data streams with recurrent concept drifts. CCP stores the running mean and standard deviation for each numeric attribute and the fraction of instances for each bin in the case of nominal attributes over a sliding window. These features are identifed as 'Conceptual Vectors' in CCP. GraphPool takes this idea further by storing a covariance matrix of attributes for each class. Cluster feature vector [\[Zhang](#page-8-23) *et al.*, 1996] was used to store information about each cluster in UClust. Authors of FiCSUM [\[Halstead](#page-7-21) *et al.*, 2023a] argue that no single meta-feature can fully represent a concept. They propose a general framework for combining various meta-features into a single representation. They propose a method for effciently computing, storing, and querying an arbitrary metafeature set as a single representation. They also propose a method for dynamic learning of meta-features that distinguishes concepts for a given dataset. According to the authors, FiCSUM enables feature selection methods, such as mutual information, to be applied to concept representation meta-features [\[Halstead](#page-7-21) *et al.*, 2023a]. The idea was initially proposed in 2021 however, in the initial version, it was identifed that introducing irrelevant meta-features may reduce performance. A new data structures which facilitates feature selection to learn the relevant meta-features was introduced in the later version[\[Halstead](#page-7-21) *et al.*, 2023a]. SELeCT [\[Halstead](#page-7-22) *et al.*[, 2022a\]](#page-7-22) maintains a distinct internal state for each classifer. It uses meta-features described in FiCSUM to describe a state. Considering the previous states, it selects the best classifer for the current state of the stream. SELeCT contains three components: a method for representing a concept as a system state, a method for computing state priors and likelihoods, and a continuous state selection statistical test to select the active state for an incoming observation.

Table [1](#page-3-1) summarises how the above-mentioned-design components were used in different [SL](#page-0-0) methods for data streams with recurrent concept drifts. It further shows that some solutions employ many techniques to address the issue, whereas others use only a few. We can also observe that techniques involving clustering and concept meta-features have gained traction in recent years.

## 4 Evaluation

It is crucial to correctly evaluate a newly proposed method or a drift detector to understand its strengths and weaknesses. Except for typical prequential evaluation and data stream cross-validation along with accuracy, kappa, and other metrics [\[Gunasekara](#page-7-1) *et al.*, 2023], novel techniques proposed for [SL](#page-0-0) on data streams with recurrent concept drifts require evaluation methods that demonstrate their suitability for such data streams. The literature explains a few evaluation methods for [SL](#page-0-0) on recurrent concept drifts. They mainly fall into three categories: i) evaluation methods that evaluate the general performance of a method on a data stream with recurrent concept drifts, ii) evaluation methods that evaluate the model selection for each concept on a data stream with recurrent concept drifts, iii) evaluation methods which evaluate drift detection methods for data streams with recurrent concept drifts.

## <span id="page-4-2"></span>4.1 Evaluating Relative Performance

Other than reporting typical prequential evaluation of a newly proposed classifer A on a data stream with recurrent concept drifts, this evaluation compares the performance of classifer A against a baseline classifer B. Early work proposed a variant of Q statistic [Gama *et al.*[, 2013\]](#page-7-23):  $Q_i$  =  $log(B_{err_i}/A_{err_i})$ , where the index *i* refers to the time-stamp, and  $A_{err}$  and  $B_{err}$  refers to the error rate of the classifiers under comparison [\[Gama and Kosina, 2014\]](#page-7-24). In more recent  $\sum ((accuracy(A) - accuracy(B))$  was proposed to evaluwork, Cumulative Accuracy Gain (CAG) [Wu *et al.*[, 2022\]](#page-8-9): ate a new method for recurrent concept drifts. CAG represents a sum of accuracy differences against a baseline at a given sample frequency. Apart from accuracy, CAG evaluation could also be applied using kappa statistics. In both the above evaluation methods, the base classifier  $B$  selection greatly infuences the fnal evaluation.

## <span id="page-4-1"></span>4.2 Evaluating Model Selection for Each Concept

Most of the [SL](#page-0-0) methods proposed for data streams with recurrent concept drifts keep a pool of classifers/buffers for each concept and attempt to retrieve the most suitable one from the pool for a given concept. To evaluate this, three measurements of context identifcation are discussed in the literature [\[Halstead](#page-7-25) *et al.*, 2021]. Proposed measurements consider concepts that are previously known and their context and model are use as nominal and discrete for a given dataset. Here, context refers to an underlying condition that results in a concept. For example, a stream may be in a given context A for a period of observations and then swap to context  $B$  over the subsequent period. At the same time, a system may use model A it has created over a period of time and then swap to model B.

 $F1_c$  measures the context linkage considering model use in these cases. It measures the strength of the relationship between each  $<$  model, context  $>$  pair, e.g.  $<$  Model A, rain >, using recall (the fraction of rain samples which occurred under Model A) and precision (the fraction of samples under Model  $A$  where it was also raining). For given  $s$  and  $c$ , where s is the time steps a given model was active and  $c$  is the time steps a given underlying context was present. The authors calculated the recall( $R$ ) and precision( $P$ ) of s on  $c$ :  $R(s, c) = \frac{|\{t | t \in s \text{ and } t \in c\}|}{|c|}, P(s, c) = \frac{|\{t | t \in s \text{ and } t \in c\}|}{|s|}$  and further calculated the F1 score:  $F1(s, c) = 2 \frac{R(s, c)P(s, c)}{R(s, c) + P(s, c)}$ .

The above is used to calculate three transparency measures. i) Average Context  $F1_c$ : is the maximal  $F1$  score obtained considering the cooccurrence of a single model and each context, averaged across all underlying contexts:  $F1_c = \sum_{c \in C} \frac{1}{|C|} \max_s F1(s, c)$ . For any given underlying context, this measures the approximate average F1 score a single model hopes to achieve. **ii**) Average System  $F1_s$ : is the maximal  $F1$  score obtained by considering the cooccurrence of each model and a single context, averthe cooccurrence or each model and a single context, averaged across all models, weighted by length of active time:  $F1_s = \sum_{s \in S} \frac{|s|}{|S|} \max_c F1(s, c)$ . This measures the average F1 score a model chosen randomly has on its closest context match, given only the system's model history. **iii**)  $s \approx c$ : the number of models which achieve a recall and precision above 80% on one underlying context. These models have the potential to predict underlying contexts.  $\mu_s = \sum_{s \in S} \frac{|s|}{|S|} \max_c F1(s, c)$ . This measures the average score a model chosen randomly has on its closest context

According to the authors,  $F1_c$  and  $F1_s$  have similar properties to the standard F1 measure, which ranges from  $\overline{0}$  to  $\overline{1}$ . The  $s \approx c$  measure ranges from 0 to the maximum number of underlying concepts present in the stream. A high  $F1_c$  indi-<br>postes that abonass in concent were successfully identified. In cates that changes in concept were successfully identified. In FiCSUM,  $F1_c$  is identified as C-F1 [Halstead *et al.*, 2023a].  $\epsilon$  measure ranges from  $\sigma$  to the maximum number of

#### 4.3 Evaluating Drift Detection on Synthetic Data Evanuaring DTHV Detection on Symmetre Dutu

MDP explains an evaluation framework for drift detection on synthetic datasets [\[Anderson](#page-7-20) et al., 2018]. As one can specify when the true drifts occur, they can be compared to when the drifts are detected. False positive rate FP is the proportion of drifts detected when no drift occurred since the last drift detection. Here, the true positive rate (TP) =  $1$  -FP. The false negative rate FN is defined as the proportion of true drifts followed by another drift before a drift detection. These measures are compared to highlight the tradeoff between Type I (FP) and Type II (FN) errors in each method. The authors also considered the drift detection delay, the mean number of instances between an actual drift, and the subsequent drift detection. Similar evaluations on drift detection and drift detection delay are also presented in other work as well [Maslov *et al.*, 2016; Huang *et al.*, 2014; Koh *et al.*, 2018].  $\frac{1}{6}$  setup in the setup setup is defined as the proportion WOIK [a](#page-8-21)s WEIT LIVIASION CL  $u_i$ , 2010, Trading Cl  $u_i$ , 2014,

#### 5 Open Source Software Spen bource bolthure

Most of the methods discussed in section [3](#page-2-3) have a GitHub fork of a popular [SL](#page-0-0) framework like [Massive Online Anal](https://moa.cms.waikato.ac.nz/)[ysis \(MOA\),](https://moa.cms.waikato.ac.nz/) scikit-multiflow, or [River](https://riverml.xyz/latest/) with the implementa-tion. LEARN++.NSE is available as a learner in MOA. [PCCF](https://github.com/av-maslov/Pccf) and [ProChange](https://github.com/cpearce/prochange) are available as separate Python programs. MOA implementations of [CPF, ECPF,](https://github.com/ingako/CPF) [MDP,](https://github.com/rand079/MDP) and [PEARL](https://github.com/ingako/PEARL-in-MOA) are available as separate repositories. [scikit-ika,](https://scikit-ika.github.io/) which is based on scikit-multifow, contains implementations of PEARL and Nacre. [FALL](https://github.com/BenHals/FALL) [\[Halstead](#page-7-26) *et al.*, 2023b] is a modular adaptive learning platform based on River. Thus it allows one to use different classifers and drift detectors from River. It contains modules to calculate some of the meta-features discussed in the section [3.5](#page-4-0) such as the ones used in [FiCSUM.](https://github.com/BenHals/FiCSUM) FALL also implements the selection mechanism and C-F1 context evaluation explained in section [4.2.](#page-4-1)  $t_{\text{FADM}}$ , scial indiction, of Kivel with the implementation

## 6 Benchmark Datasets

Some of the commonly used synthetic data generators such as SEA, Hyperplane, Agrawal, Random Tree, LED and different concept drift simulators are available in [MOA.](#page-0-0) Although realworld datasets Electricity and Sensor [Angel *et al.*[, 2016\]](#page-7-5) are widely used in [SL](#page-0-0) literature for data streams with recurrent concept drifts, their exact concept recurrences are unclear.

<span id="page-5-0"></span>

Figure 3: Different temperature contexts which influence the wingbeat frequency of Aedes aegypti mosquitoes in Aedes-Culex dataset. Source: [\[Moreira dos Reis](#page-8-3) *et al.*, 2018].

On the other hand, real-world datasets Aedes-Culex, Aedes-Sex, Arabic-Digit, CMC, Handwritten-QG, and Wine contain clear recurring contexts [Moreira dos Reis *et al.*, 2018]. and deal recurring conceases problem dos reds et al., 2010).<br>For example, figure [3](#page-5-0) shows the different temperature contexts that infuence the wing-beat frequency of Aedes aegypti mosquitoes in the Aedes-Culex dataset. FiCSUM uses these contexts to identify resulting concepts. The building electricity demand simulation dataset used in [Wu *et al.*[, 2023\]](#page-8-1) also contains recurrent concepts.

## 7 Future Directions

Considering the recent developments in [SL](#page-0-0) and machine learning in general, this section aims to explore possible intersections of those felds with [SL](#page-0-0) on data streams with recurrent concept drifts.

## 7.1 Unlabeled Data and Concept Evolution

Apart from one recent work [\[Namitha and Santhosh Ku](#page-8-16)[mar, 2020\]](#page-8-16), there has not been much attention paid to unsearch community. Considering that most real-world data is unlabeled, this could be an exciting research direction the [SL](#page-0-0) are community working on recurrent concept drifts could peruse. labeled data streams with recurrent concepts among the re-

siders evolving target variables. Here at  $j + 1$ , new set of Section [2](#page-1-1) defnition of a recurrent concept drift at concept  $j+1$  only considers the recurrent concepts where  $P_j(y|X) \neq$  $P_{i+1}(y|X)$ . On the other hand, *concept evolution* only conclasses emerge compared to  $j$ :  $P_j(y) \neq P_{j+1}(y)$  [\[Gao](#page-7-4) *et al.*[, 2020\]](#page-7-4). Here, the distribution shift is in the label data instead of the input data. Apart from completely new (previously not seen) classes at  $j + 1$ , [\[Masud](#page-8-24) *et al.*, 2011; Gao *et al.*[, 2020\]](#page-7-4) considers concept evolution with the reappearance of any previously seen class that was not available at  $j$ . There are only a few works in this area of concept evolution with recurrent classes. Most of the techniques discussed in section [3](#page-2-3) could be applied in this setting. Thus, we see this as a natural expansion of current [SL](#page-0-0) on data streams with recurrent concept drifts.

## 7.2 Online Continual Learning

[Online Continual Learning](#page-0-0) also considers online learning of tasks with different label/input distributions [\[Gunasekara](#page-7-1) *et*



Figure 4: [Continual Learning](#page-0-0) Datasets [\[Verwimp](#page-8-25) *et al.*, 2023].

published in  $\mathcal{L}$  and  $\mathcal{L}$  is details. Black circles are recently proposed, more recently pro al.[, 2023\]](#page-7-1). But in [OCL,](#page-0-0) task reoccurrence is not guaranteed.<br>Here the learning system is forced to remember old tasks aware of the drift points of Here, the learning system is forced to remember old tasks. aware of the drift points of Hence, after training on a given task, instances from all the task, the OCL method is  $\epsilon$ *et al.*[, 2023\]](#page-7-1). Thus, forgetting of previous tasks after learning teres a new task can be calculated. previous tasks are considered in the evandation requirement of an the affecting the same labels are used. For more details and the same labels are used. For more details and the same labels are used. For more details and t depict how data distributions *X* and the available labels *Y* change during training. The yellow circles areas are proportional to how many papers  $\mathbf{u}_i$  refers to be not benchmarks where multiple datasets with the same labels are used. For more details and  $\mathbf{u}_i$ Hence, after training on a given task, instances from all the task, the OCL method is ev previous tasks are considered in the evaluation [\[Gunasekara](#page-7-1) of all the already learned tas

a how also can be calculated.<br>[OCL](#page-0-0) considers two settings with different types of distri-<br>huion shifte: Online Domain Incremental Continual Learn bution shifts: [Online Domain Incremental Continual Learn](#page-0-0)[ing \(ODICL\)](#page-0-0) and Online Class Incremental Continual Learn-<br>ment over past tasks. ing (OCICL). ODICL is similar to SL on data streams with concept drifts where distribution shifts are in the input<br>data [Gunasekara *et al.*, 2023]. On the other hand, OCICL data [Gunasekara *et al.*, 2023]. On the other hand, [OCICL](#page-0-0) and focuses online learning on tasks with different label distribution and the concept explicitly tions. It is similar to [SL](#page-0-0) with concept evolution. Considering<br>cintos for each recurrent c al., 2023] explains how some of the ideas from SL on recurrictions. repository management techniques to manage a pool of Neu-<br>nasekara et al. 2023] One  $\frac{d}{dt}$  and  $\frac{d}{dt}$  on  $\frac{d}{dt}$  can concent drifts could be useful in OCL. Specifically drift  $\alpha$  detection and prediction to detect and predict tasks, model<br>and other evaluation r ral Network (NN)s and model selection techniques to select a<br>forgetting to evaluate [Neural Network](#page-0-0) for prediction on instances from a past task.  $\frac{101 \text{ g e} \cdot \text{m}}{\text{reincarnations of the same } c}$  $\frac{1}{2}$  cosen discrete intervals is a reasonable approximation of  $\frac{1}{2}$  car exploring the cosenable  $\frac{1}{2}$  car exploring the cosenable discrete intervals the cosenable discrete intervals of  $\frac{1}{2}$  car explorin al., 2023] explains how some of the ideas from [SL](#page-0-0) on recur-<br>rithm. Similar to current s [ing \(OCICL\). ODICL](#page-0-0) is similar to [SL](#page-0-0) on data streams<br>with concent drifts where distribution shifts are in the input

On the other hand, some of the real-world [OCL](#page-0-0) datasets reincarnations of the same concept. such as: CORe50 and [Online Domain Incremental Continual](#page-0-0)  $\frac{1}{2}$  in the SO and South  $\frac{1}{2}$  $t_{\text{column}}$  vehicles concerned control many of the datasets discussed in [Verwimp *et al.*, 2023] can  $\bullet$  **Conclusions** b[e](#page-0-0) used to evaluate SL [m](#page-0-0)odels for data streams with recurrent concept drifts. Figure [4](#page-6-0) contains a summary of different real-<br>world OCL datasets. As per figure 4, some datasets contain streams with recurrent world [OCL](#page-0-0) datasets. As per figure [4,](#page-6-0) some datasets contain streaments clear distribution shifts going from one task to the other, and tance clear distribution shifts going from one task to the other, and<br>in most of those datasets, the start and end of the task are sidering concept recurrence clearly defined to support the [OCL](#page-0-0) evaluation. Such real-<br>the i world datasets can be very useful in evaluating [SL](#page-0-0) methods curr proposed for data streams with recurrent concept drifts. ation<br>imp  $\frac{1}{1}$  for  $\frac{1}{1}$   $\frac{2022}{1}$   $\frac{1}{1}$ Learning version of CORe50 [Gunasekara *et al.*, 2022] and<br>Learning version of CORe50 [Gunasekara *et al.*, 2022] and ral and gradually changing distribution shifts, an exceltonomous driving. Self-driving vehicles can change ur-

#### 7.3 Evaluation for Recurrent Concept Drifts ods<br>ods  $\text{imp}$ tonomous driving. Self-driving vehicles can change ur-7.3 Evalu

the main immation of the performance evaluation methods that they require a baseline method. Thus, the performance of the proposed algorithm is denoted. They the performance of  $\mu$ the proposed algorithm is dependent upon the performance of the baseline method. Here, one could choose a general SL al-<br>the baseline method. Here, one could choose a general SL alproposed for recurrent concept drifts. This does not allow us fancy. We hope future proposed for recurrent concept drifts. This does not allow us<br>to evaluate how accurately the proposed algorithm performs on recurrent concept drifts. On the other hand, model selec-<br>drifts. The main limitation of the performance evaluation methods quires into Online Contains the performance evaluation methods quires into Online Contains the performance of the performance of different states with recurrent cl discussed in section [4.1](#page-4-2) for SL on recurrent concept drifts is the baseline method. Here, one could chow<br>gorithm as the baseline to evaluate an alg on receivent concept using. On the other final accuracy, however we note that the BWT metric is the proposed the baseline traingorium as u<br>proposed for on recurrent gorithm as the baseline to evaluate an algorithm specifically<br>proposed for recurrent concept drifts. This does not allow us

<span id="page-6-0"></span>performance. **They** do not give us an indication of the model's predictive tion evaluation methods discussed in section [4.2](#page-4-1) only consider selecting the correct model for the relevant concept.

 $\mathbf{S}$  and common benchmarks for continual learning in computer vision, with a focus on computer vision,  $\mathbf{S}$ depict how data distributions *X* and the available labels *Y* change during training. The yellow circles areas are proportional to how many papers of the selected baseline. Fossible inspirations could come<br>from [Online Continual Learning](#page-0-0) evaluations [\[Gunasekara](#page-7-1) *et*  $\frac{Permited}{MNST}$  MNST algorithm's suitability when learning from a data stream with *et al.*, 2023]. Different tasks with distribution shifts in the  $F_{\rm spec}$ *et al.*[, 2023\]](#page-7-1). Here, the current task's performance of the The clear of the selected baseline. Possible inspirations could come  $S<sub>g</sub>$  specifically is quite similar to [Stream Learning](#page-0-0) [\[Gunasekara](#page-7-1)] Continual Learn- formance, with lower forgetting indicating a model improvealgorithm, as evaluation is a bit subjective to the performance er learning teresting metric discussed in [OCL](#page-0-0) is forgetting [\[Gunasekara](#page-7-1)  $\begin{array}{ll}\n\text{for all } \text{even} \\
\text{S of distinct vectors} \\
\text{S of distinct vectors} \\
\text{S of different vectors} \\
\text$ IFOR Office Continual Learning evaluations (Guitasekara *et*<br>atasets [Verwimp *et al.*, 2023]. *al.*, 2023]. [Online Domain Incremental Continual Learning](#page-0-0) community could further explore. When evaluating the perinput data appear in the stream. The evaluation method is aware of the drift points of the stream. After learning a new task, the [OCL](#page-0-0) method is evaluated against separate test sets of all the already learned tasks. Apart from accuracy, one inment over past tasks.

the similarity in two settings: SL and OCL [Gunasekara *et* sights for each recurrent concept. It can help identity which<br>recurrent concept performs best with which proposed also-L [Gunasekara *et* recurrent concept performs best with which proposed algo-Figure 3.1 on recur-<br> $S_{\text{res}}$  rithm. Similar to current stream learning evaluation meth-Specifically, drift ods, this new evaluation can be applied with accuracy, kappa, ral Network (NN)s and model selection techniques to select a<br>Neural Matricela for production on instances from a post tool.<br>Torgetting to evaluate the model improvement over different  $t_{\text{total}}$  a past task. reincarnations of the same concept.  $\mu$ , 2025 explains now some of the racis from 5D on recurrichm. Similar to current stream learning evaluation meth-<br>rent concept drifts could be useful in [OCL.](#page-0-0) Specifically, drift ods, this new evaluation can be applied focuses online learning on tasks with different label distribu-<br>tions. It is similar to SI, with appeart avalytion. Considering Foll considering sights for each recurrent concept. It can help identify which detection and prediction to detect and predict tasks, model<br>repository management techniques to manage a pool of Neu and other evaluation metrics discussed in SL literature [Gute a pool of Neu-<br>nasekara *et al.*, 2023]. One could also use a similar metric as For data streams with recurrent concept drifts, if the start and end points of a concept and its relevant recurrent concept are known, then one can track the performance of recur-

## 8 Conclusions

It is with recurrent that This survey focuses on Stream Learning methods for data of different incales that the street in the stream section of clades for Clades for Clades examples that utilise the impor- $\alpha$  to the other, and tance of SL on data streams with recurrent concept drifts contting SL methods currently available methods, their design components, evalufunty of the labels ation methods, benchmarks, and the availability of software implementations. It highlights the need for evaluation meth- $\frac{1}{\text{performed}}$  ions for future research. 1 of the task are sidering concept recurrence in the data streams generated by tion. Such real-<br>the increasing digitization processes. The survey explains the ethods quires into Online Continual Learning and Concept Evolution<br>Lie intersections and directions. **EXECUTE BENCHMARKS THAT CONCEPT DETERM**<br>The ods that do not use a baseline algorithm. Furthermore, it inwith recurrent classes to fnd possible intersections and direc-

e performance of the state of the research.<br>he performance of though we see the importance of explainability in recure a general SL al-<br>rent concept drifts, where one explains the reasons for recur-<br>rithm specifically are recorded and recorded the series of the state in-set. As referred to in Section 2.1, there can be a stream in the stream in the m<br>does not allow us fancy. We hope future work in explainable [Stream Learning](#page-0-0) does not allow us and the more future work in explainable stream Learning gorithm performs would lay the foundations for explaining recurrent concept ithm specifically rences, explainable [Stream Learning](#page-0-0) itself is still in its in- $\frac{1}{2}$  chines, with indrifts.

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